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December 2, 2020

CS-104

Algorithm (Accuracy)

1. Start Robot
2. Roll 0° at 55 speed for 1.9 secs
3. Roll 90° at 40 speed for 2.52 secs
4. Roll 0° at 40 speed for 2.8 secs
5. Roll 90° at 52 speed for 1 sec
6. Roll 90° at 255 speed for 1.5 secs
7. Roll 180° at 99 speed for 4 secs
8. End program